



ROMANSY 16: Robot Design, Dynamics and Control (CISM International Centre for Mechanical Sciences)

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The aim of this publication is to present the research results in robotics that are now state-of-the-art, and indicate the possible future lines of development. To effectively work and cooperate with us, robots must exhibit abilities that are comparable to those of humans. The book describes the ongoing efforts to design and develop human-friendly robotic systems that can safely and effectively interact and work with humans.

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